

Date :13 Dec 21 (v1)



Enquiry N°:

Created by: DB / Approved by: JD

SERVO MOTOR - 060LDB305LGCTG100620-SGV1

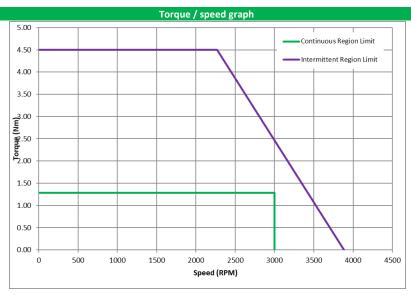
SMA507 060LDB305LGCTG100620-SGV1

AGV Solution Motor + Gearbox + Wheel
Up to 400kg Payload



Definition					
Туре	Unimotor HD				
Frame Size (mm)	060				
Voltage	L	Ultra-Low Voltage			
Magnet type	D	High Dynamic			
Frame Length	В				
Speed (min ⁻¹)	30	3000 @48Vdc - 1500@ 24Vdc			
Brake	5	Braked Flying lead power (0.5 m) with RoboteQ drive connection			
Connection type	L				
Output shaft	G	Integrated Gearbox Shaft			
Feedback device code	СТ	4096ppr incremental encoder (CTD/Motion)			
Inertia & thermistor	G	Standard inertia + No thermistor			
PCD (Gbox)	100	100 (Gear box)			
Shaft Diameter	620	G BOX output			
Fan Box	-				
Insulation class	F				
UL Motor / UL Stator	UL Stator				

Nominal characteristics						
Motor Ambient Temperature (°C)	40	Drive Fsw (kHz)	12			
Motor Stall Torque (Nm)	1.28	Stall Current (A)	9.79			
Rated Torque (Nm)	1.28	Nominal Current (A)	9.79			
Motor Peak Torque (Nm)	4.5	PeaK Current (A)	29.37			
Rated Power (kW)	0.40	Kt (Nm/A)	0.13			
Winding Thermal Time Constant (s)	55	Ke (V/kmin-1)	8.30			
Number of Poles	10	R (ph-ph) (Ohm)	0.23			
Maximum Cogging (Nm)	0.02	L (ph-ph) (mH)	0.7			
Inertia Motor + Gearbox (kg.cm²)	~0.5	Weight Motor + Gearbox (kg)	~6.0			
Ingress Protection Level (IP)	IP54					
Brake	Spring-applied	Static Torque (Nm)	1.524			
Release Time (ms)	50	Backlash (°)				
Brake Supply Voltage (V)	24.0	Brake Coil Power (W)	7.2			



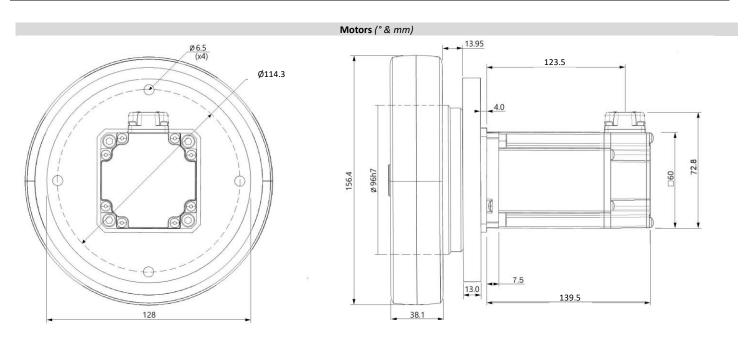
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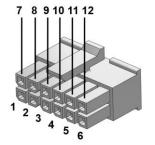


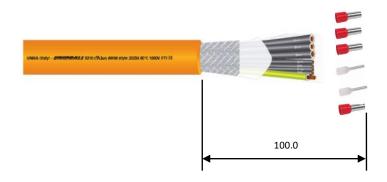
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	Motor electrical interface Connectors option:						
	Feedback device code:			Connection type:			
	CT – 4096ppr incremental encoder			L – Power & Signal flying leads Roboteq connection			
1	Power	7	CH A			U	Black 1
2	S1	8	-			V	Black 2
3	S2	9	СНВ			w	Black 3
4	S3	10				Earth	Green/Yellow
5	GND	11				Black	Brake
6		12				White	Brake
Si	Signal Cable: 500mm (from gland to customer end)			Power Cable: 500mm (from gland to customer end)			
12	12-Way MOLEX Connector, Molex part number 43025-1200, loom with PVC			Cable 4 + 2 core orange PUR screend			
ja	jacket.			4 x 1.0mm ² wires 300/500V			
				2x 0.5mm² wires			
				Cable O/D 9.8mm			
				With red ferrules for power & earth, white ferrules for brake			









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Gear Box characteristics				
Ratio	9	Backlash (arc/min)	≤7	
Stages	1	Radial Load (Fr, N) @ Fa=0, Input Speed Nom	3500	
Inertia (kg.cm²)	~0.2	Radial Load MAX (Fr, N)	7250	
Weight (kg)	2.7	Axial Load (Fa, N) @ Fr=0, Input Speed Nom	2200	
Efficiency	95%			

